

Co-location and validation of PAZ observations with polarimetric weather radars

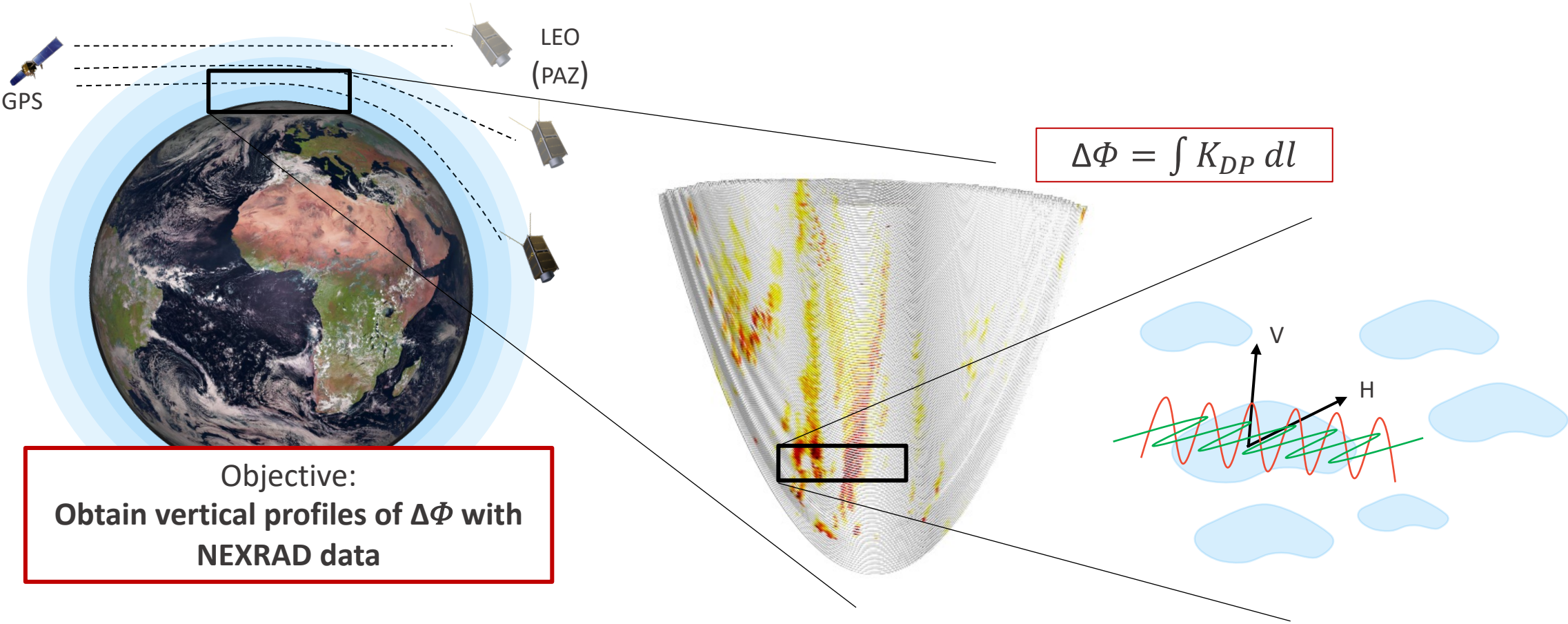
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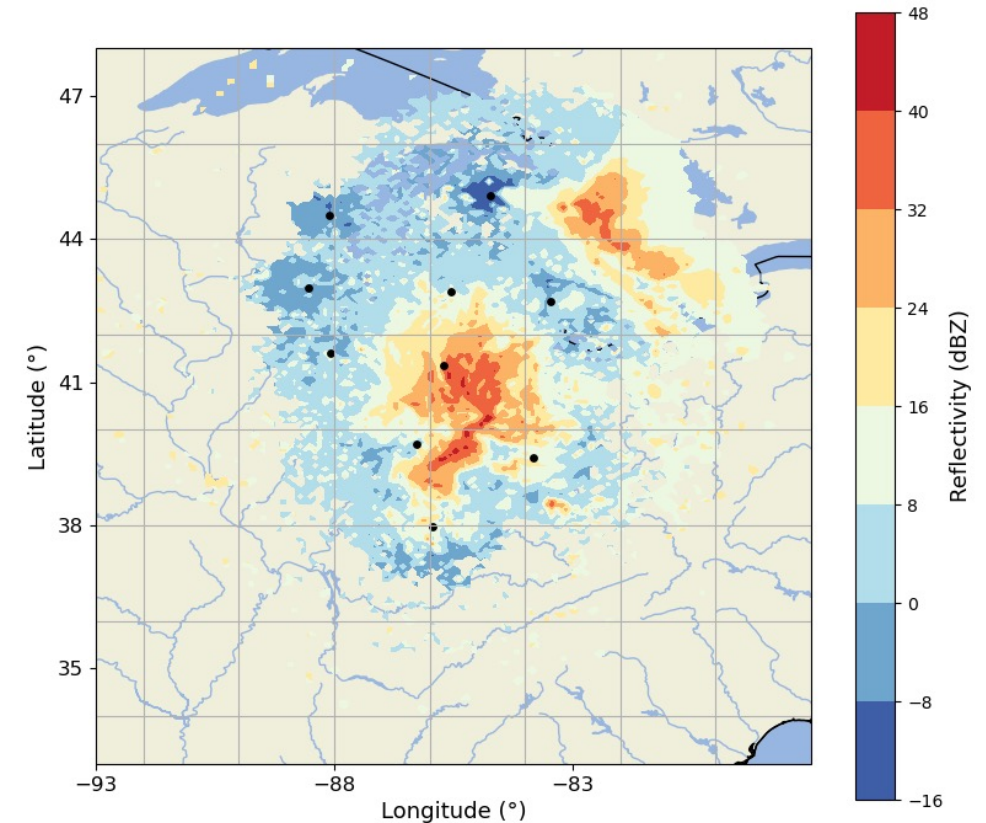
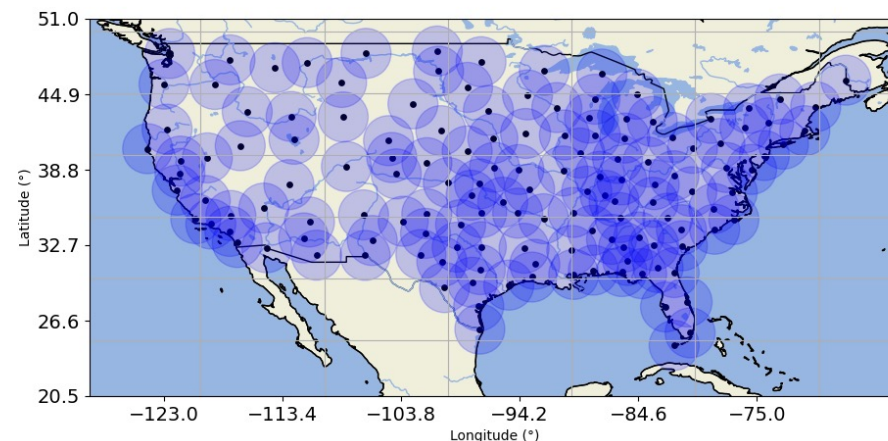
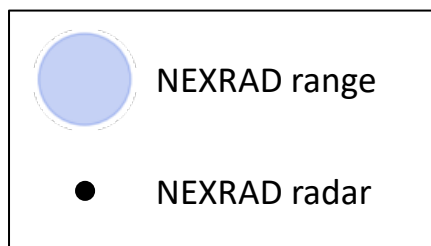
Polarimetric-RO

For horizontally oriented hydrometeors: $\Delta\Phi = \Phi_H - \Phi_V > 0$



NEXRAD

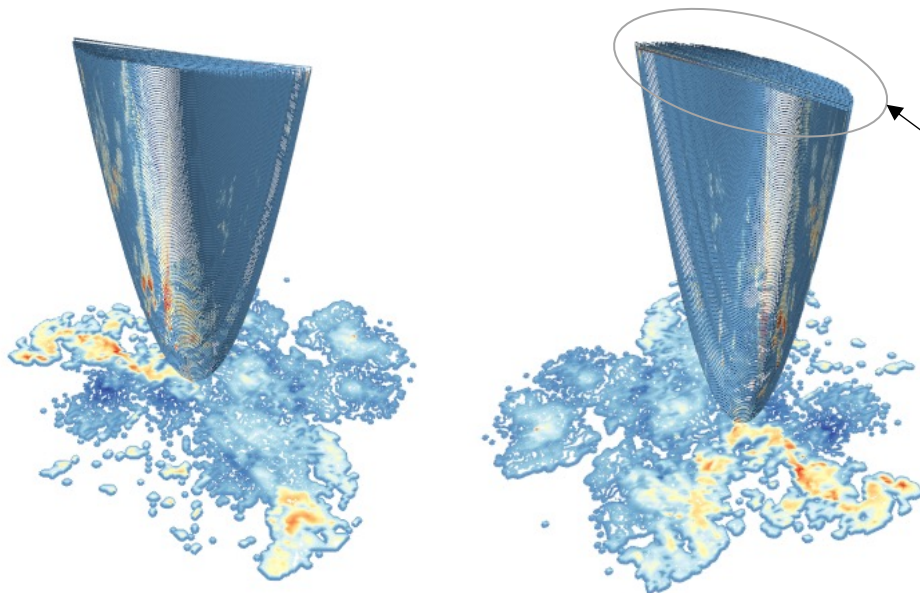
- NEXRAD radars provide reliable ground-based measurements, which can serve as ground truth data for assessing the accuracy and performance of the PRO technique.
- NEXRAD radars offer high spatial resolution and broad coverage over the US territory.
- NEXRAD radars have dual-polarization capabilities, providing variables that can be compared to the differential phase shift obtained with PAZ.



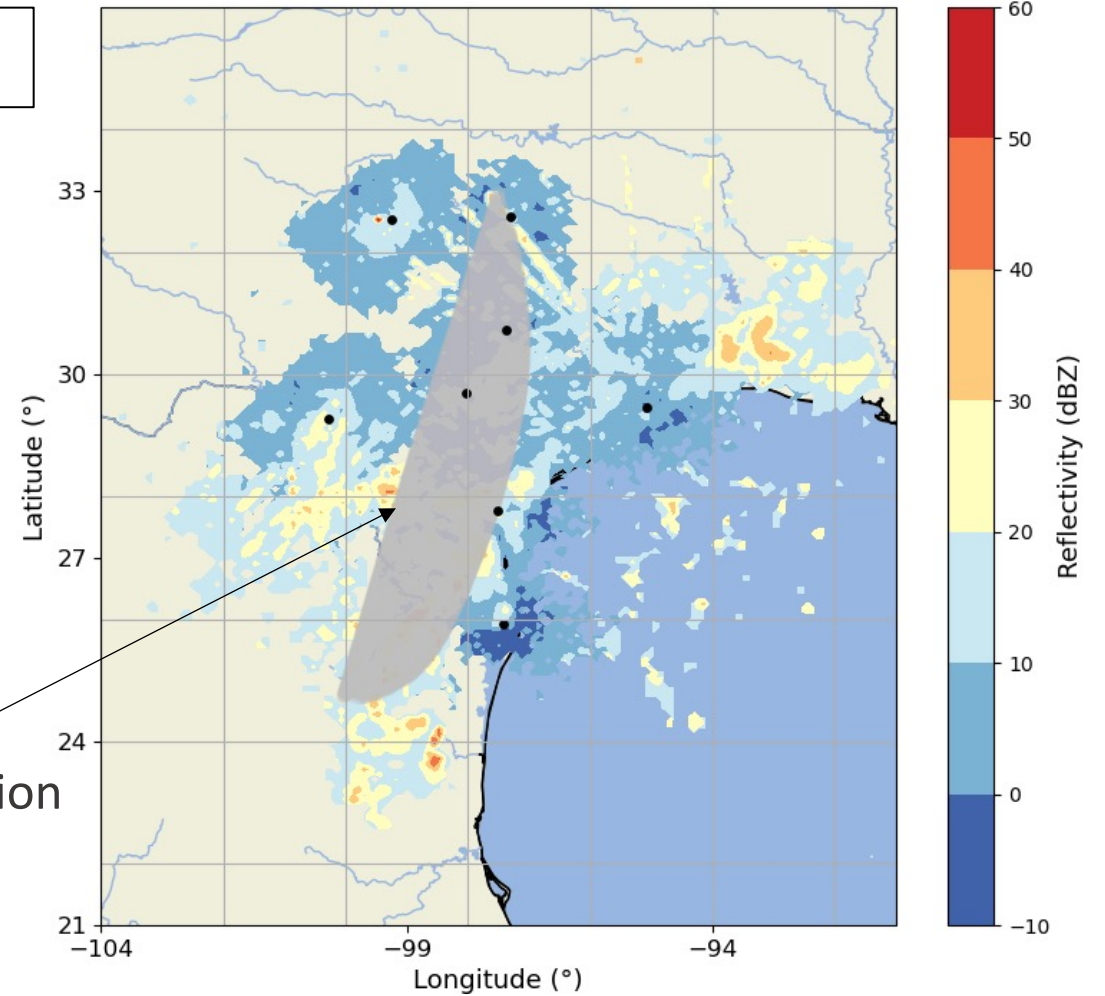
Co-located observations

- NEXRAD Level II dataset
- Time difference < 8 minutes
- Minimum distance between radar and PRO < 250 km
- Total of ~3200 observations

● NEXRAD radar

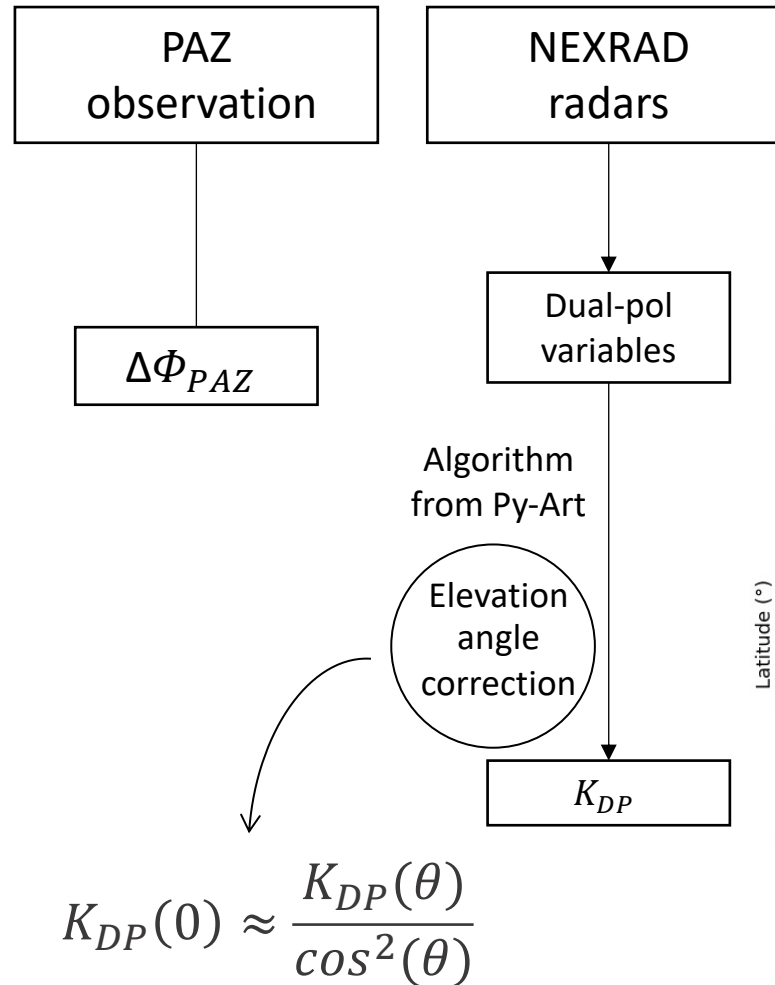


2D projection
of PRO rays

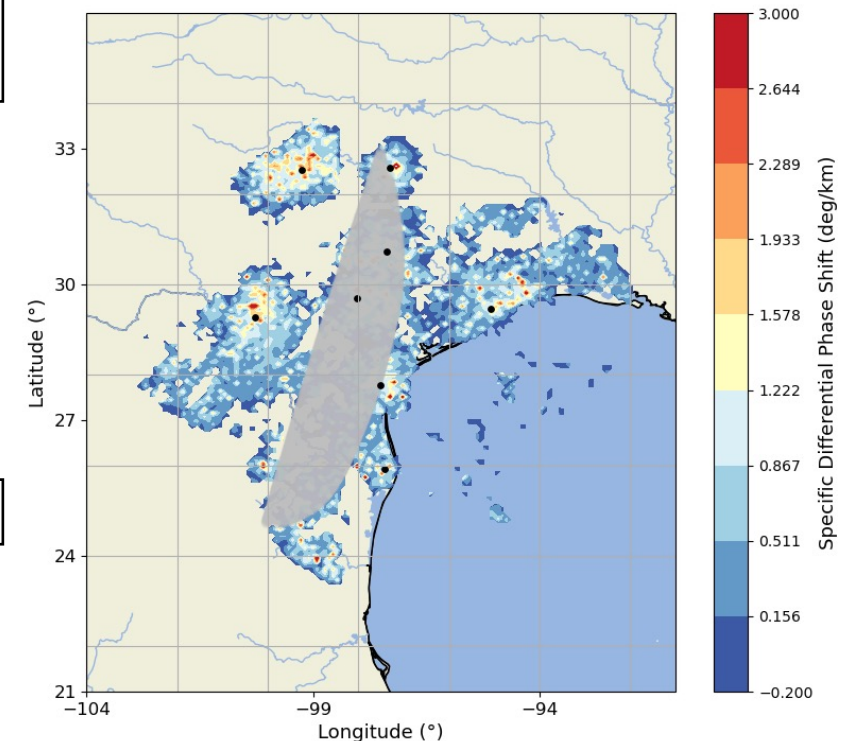


Kdp calculation

- Radar data treatment with **Py-Art**
- Calculation of Kdp based on the method developed by Vulpiani ([Vulpiani et al. 2012](#), [Vulpiani et al. 2015](#))
 - Four step process to estimate K_{DP}
 - K_{DP} is estimated through computing the finite difference over the raw Ψ_{DP} field over a moving window of user-defined size
 - Validity of the K_{DP} values are compared to a set of defined thresholds
 - Ψ_{DP} is reconstructed from the processed K_{DP} field
 - final K_{DP} estimate is obtained from the reconstructed Ψ_{DP} field through using finite differencing once more

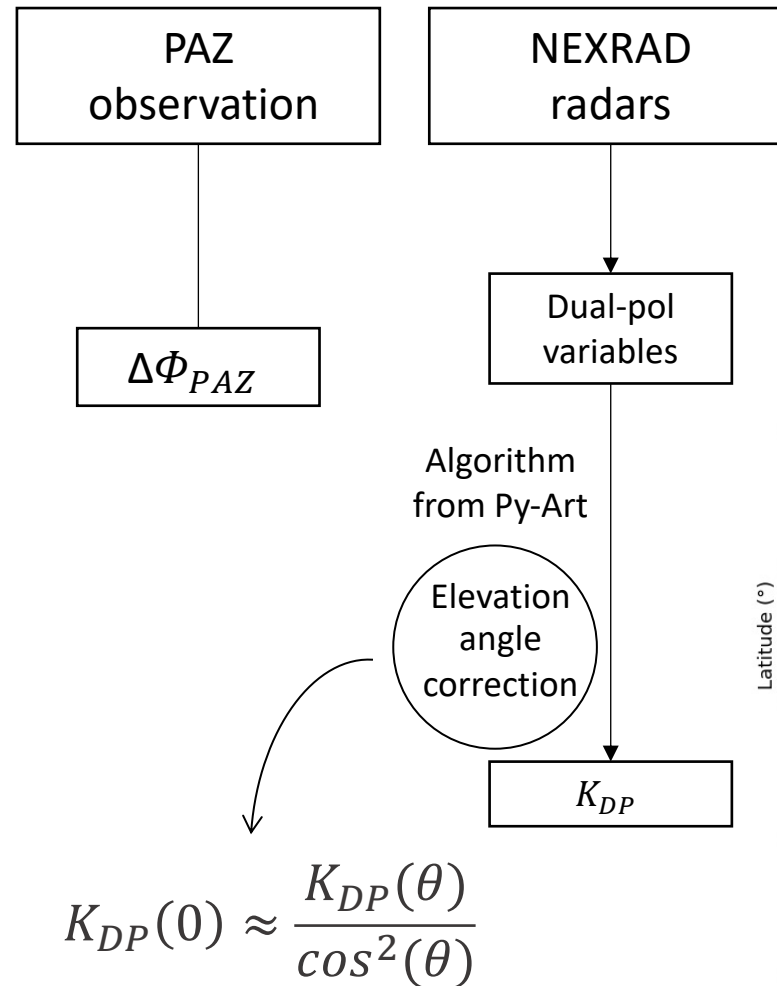


$$\Delta\Phi = \int K_{DP} dl$$

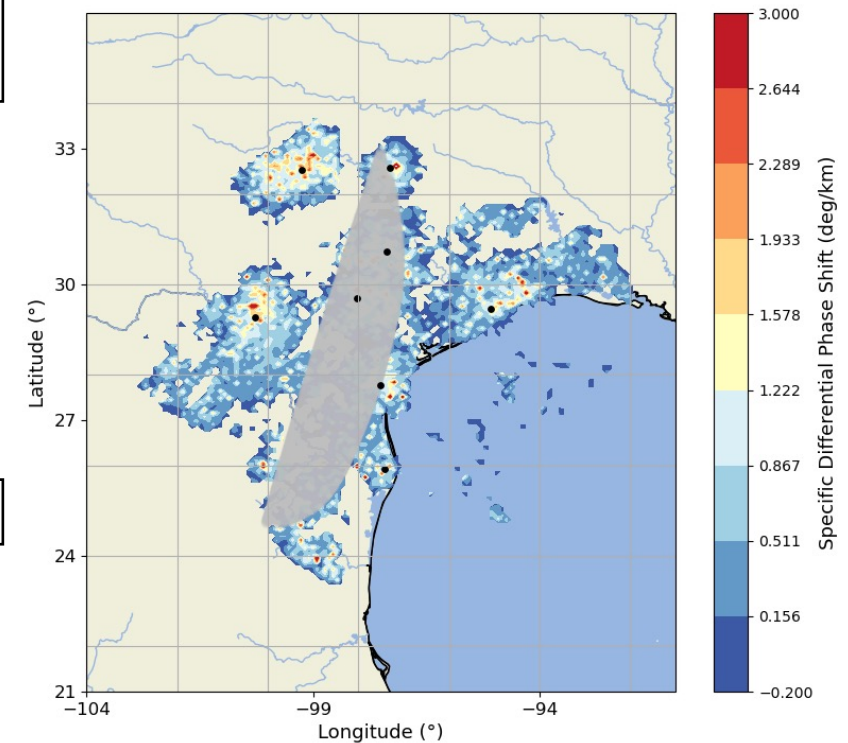


Kdp calculation

- Calculation of K_{DP} based on the method developed by Vulpiani ([Vulpiani et al. 2012](#), [Vulpiani et al. 2015](#))
- Input parameters
 - **Number of iterations**
 - **Window size**
 - **Filtration of Ψ_{DP}**
 - Censor it where ρ_{HV} is lower than 0.65
 - Unravel angles when strong discontinuities are detected
 - Remove very short sequences of valid data
 - Apply a median filter on every profile



$$\Delta\Phi = \int K_{DP} dl$$

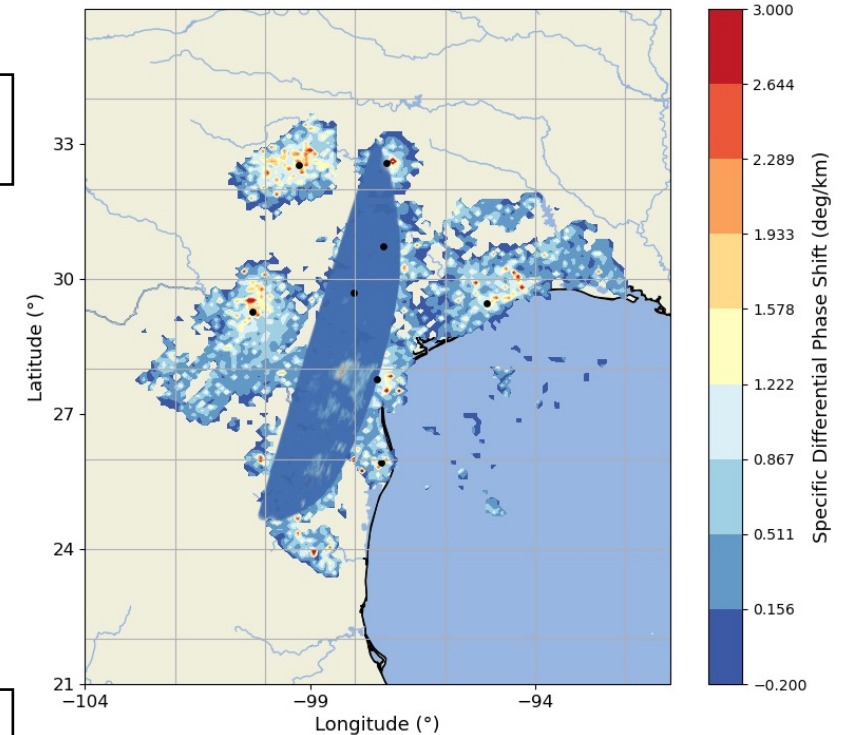
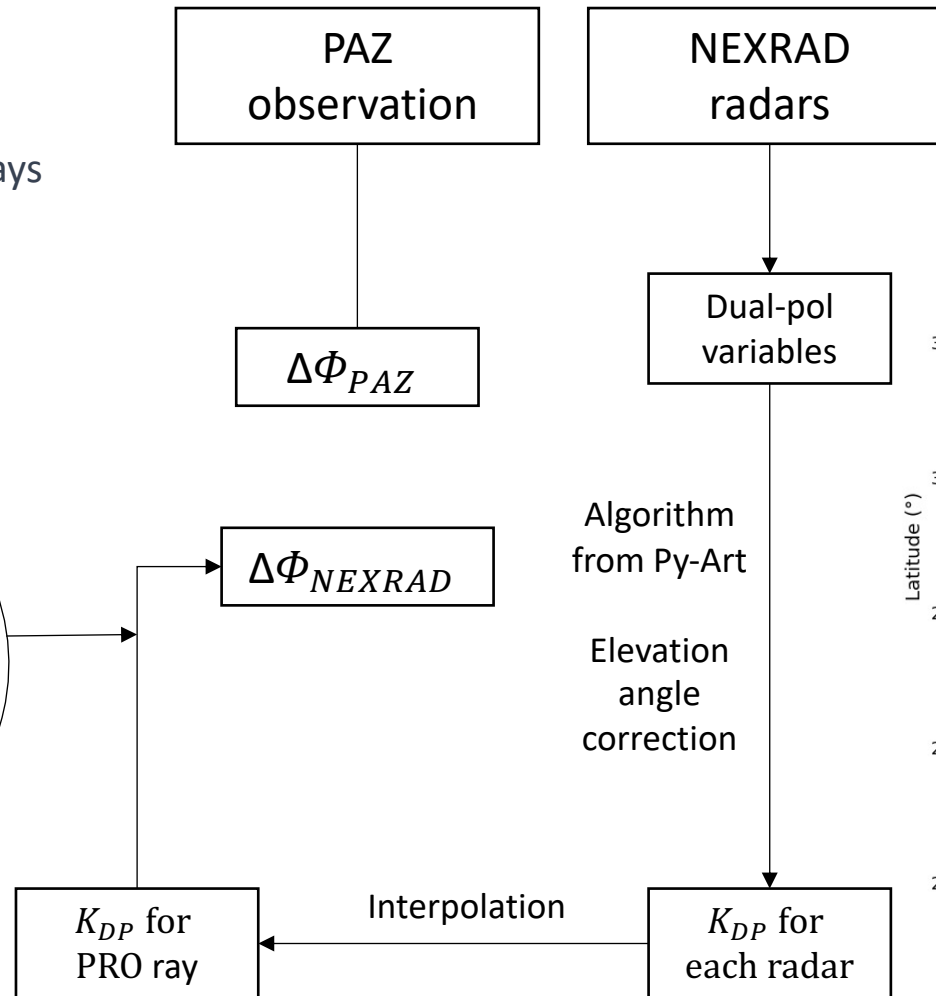


$\Delta\Phi$ calculation

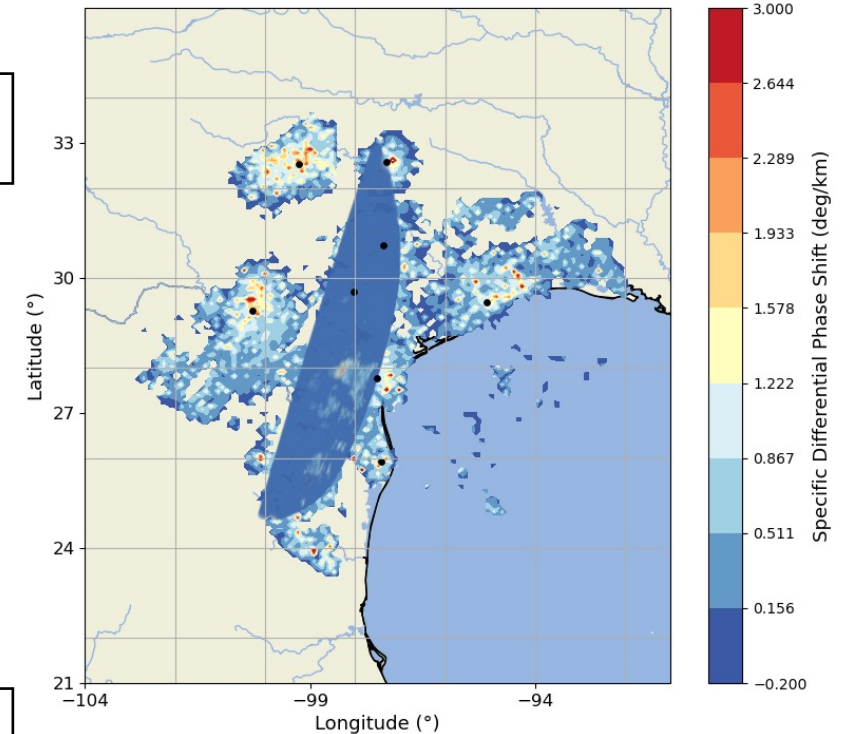
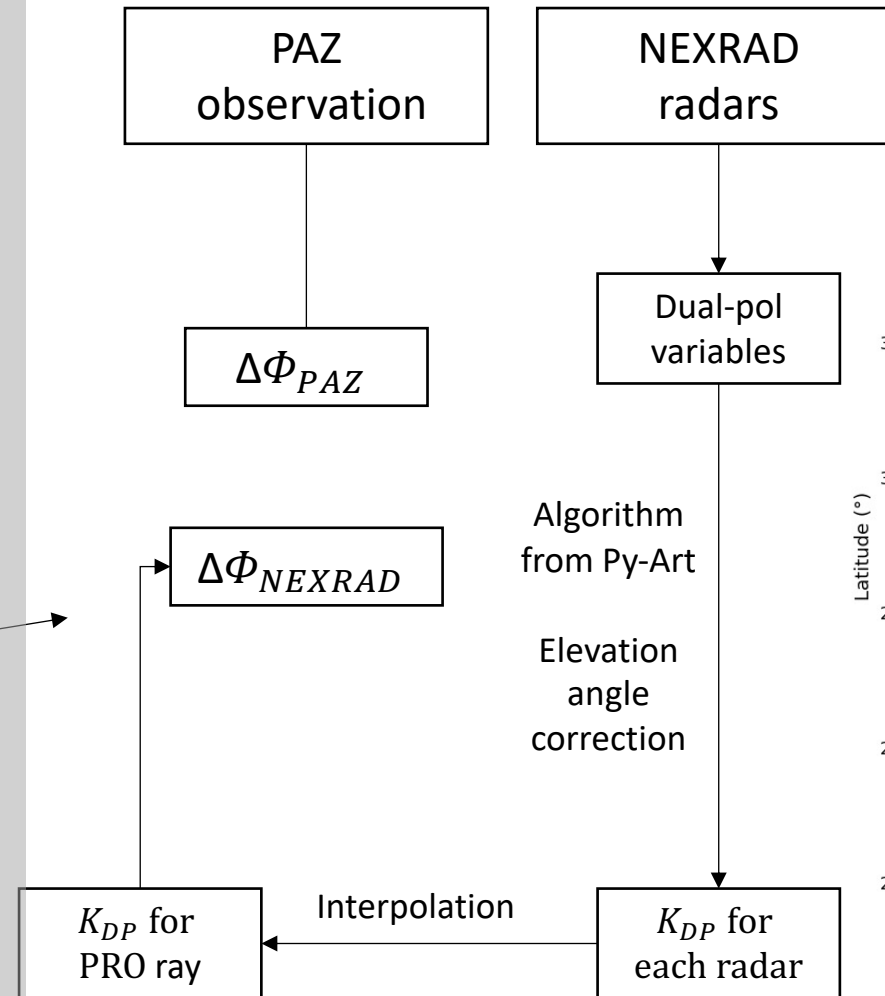
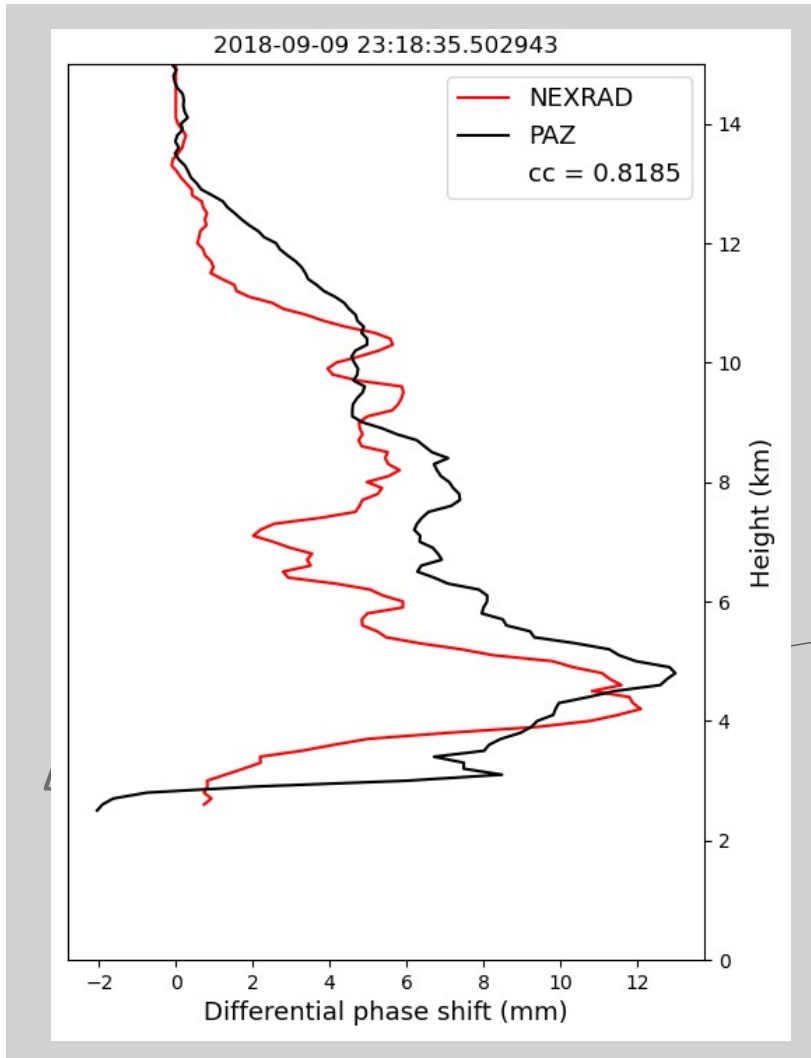
- Interpolation of K_{DP} into the PRO rays
- Integration of K_{DP} for each PRO ray

$$\Delta\Phi = \int K_{DP} dl$$

$$\Delta\Phi \text{ (mm, L band)} = \Delta\Phi \text{ (degrees, S band)} \cdot \frac{\lambda_S}{\lambda_L} \cdot \frac{\lambda_L}{360}$$



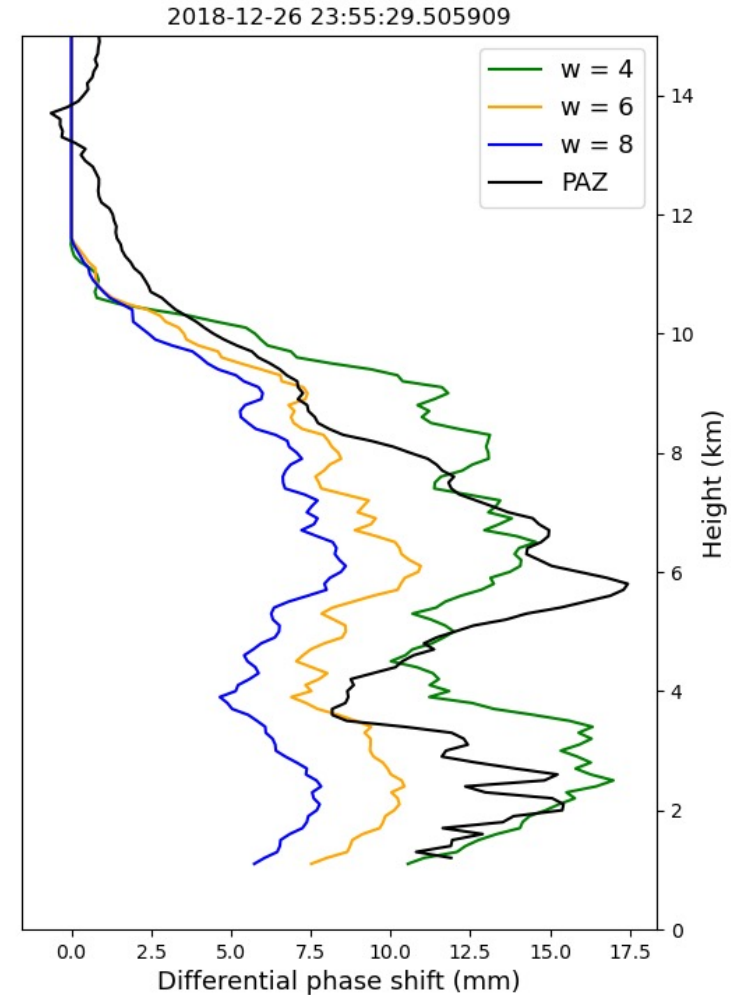
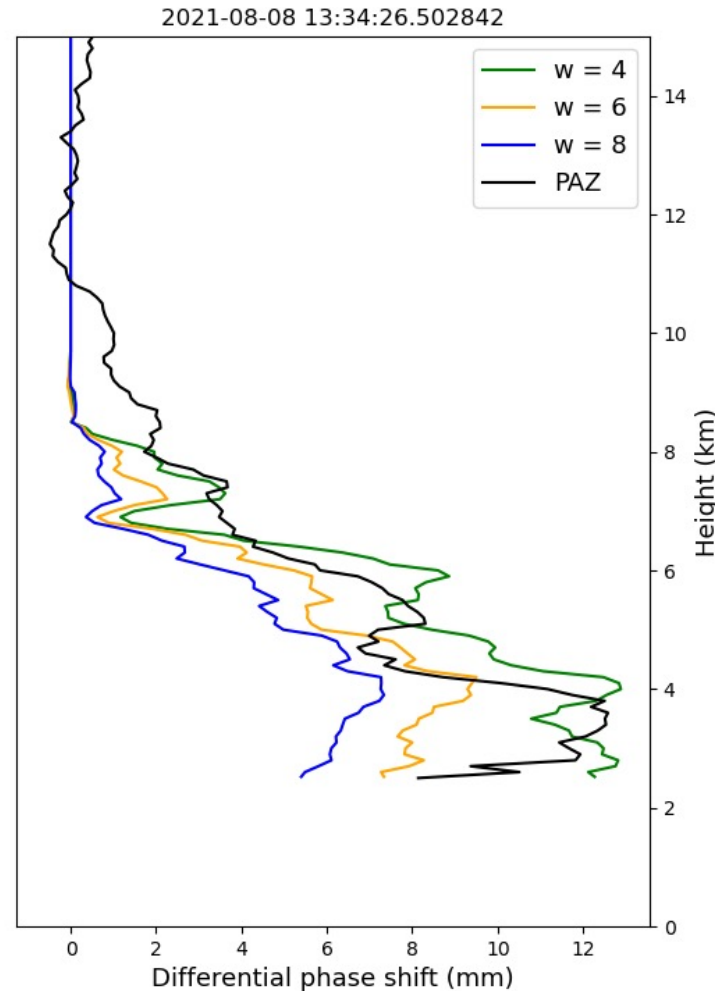
$\Delta\Phi$ calculation



Analysis in terms of window size

size

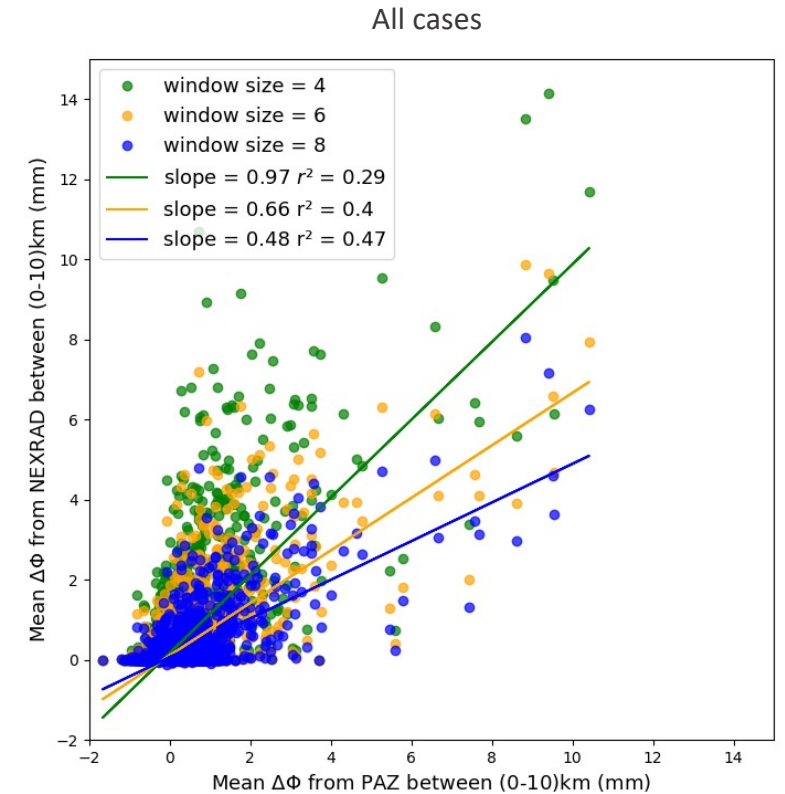
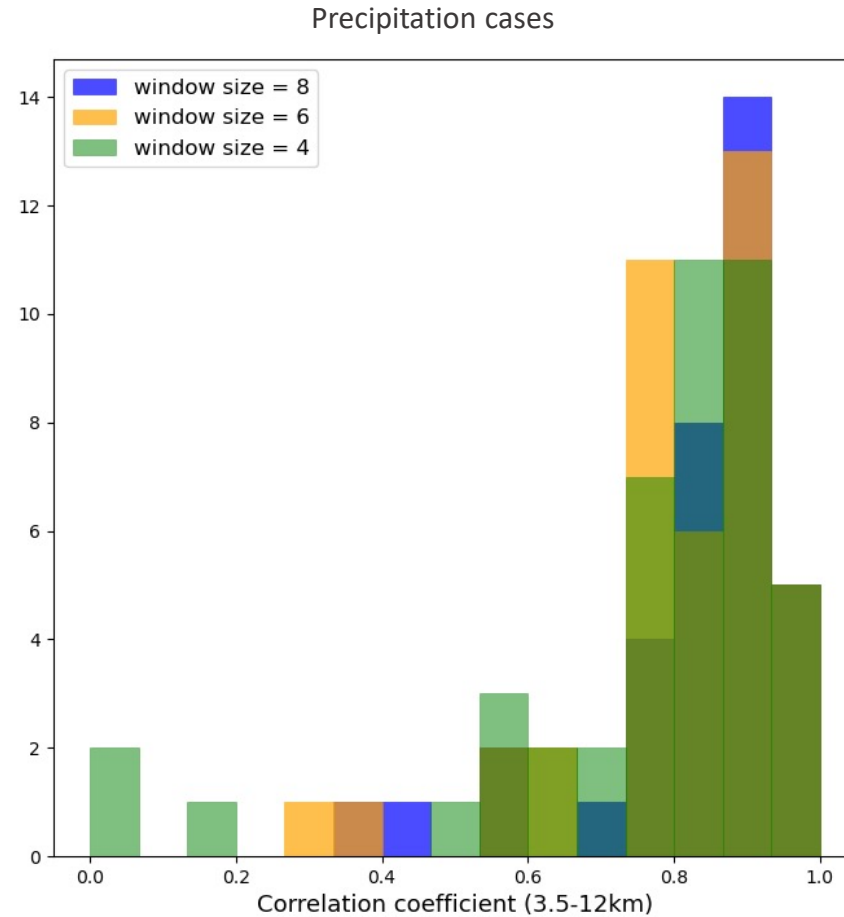
- **Window size:** represents the smoothing used for computing K_{DP}
- The size of the moving window and the magnitude of $\Delta\Phi$ are inversely proportional
- Most of the peaks are represented with all window sizes
- Essentially what changes is the module



Analysis in terms of window size

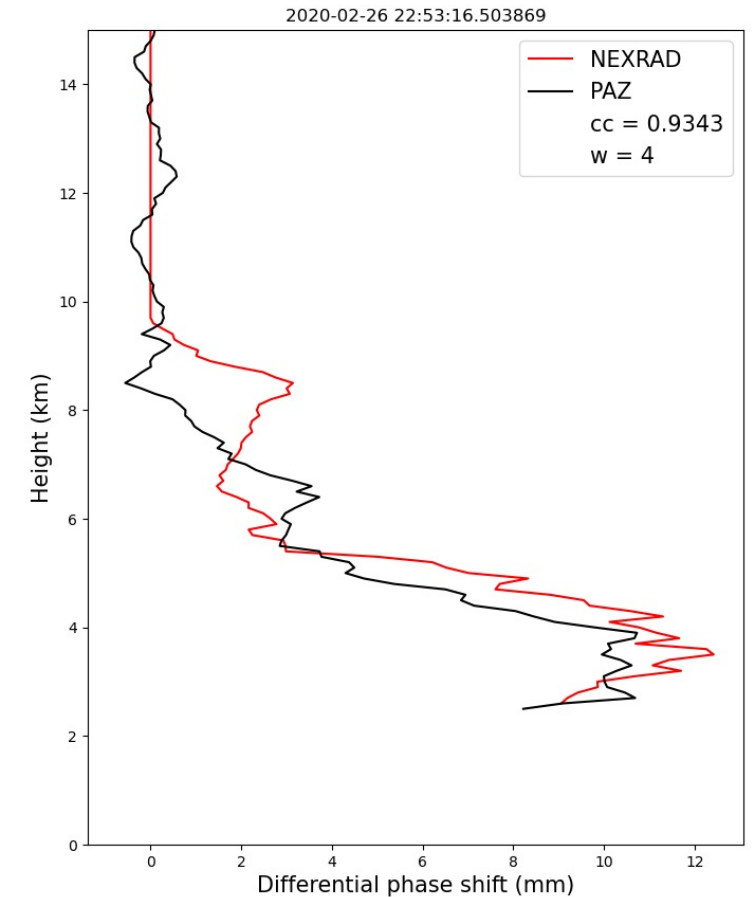
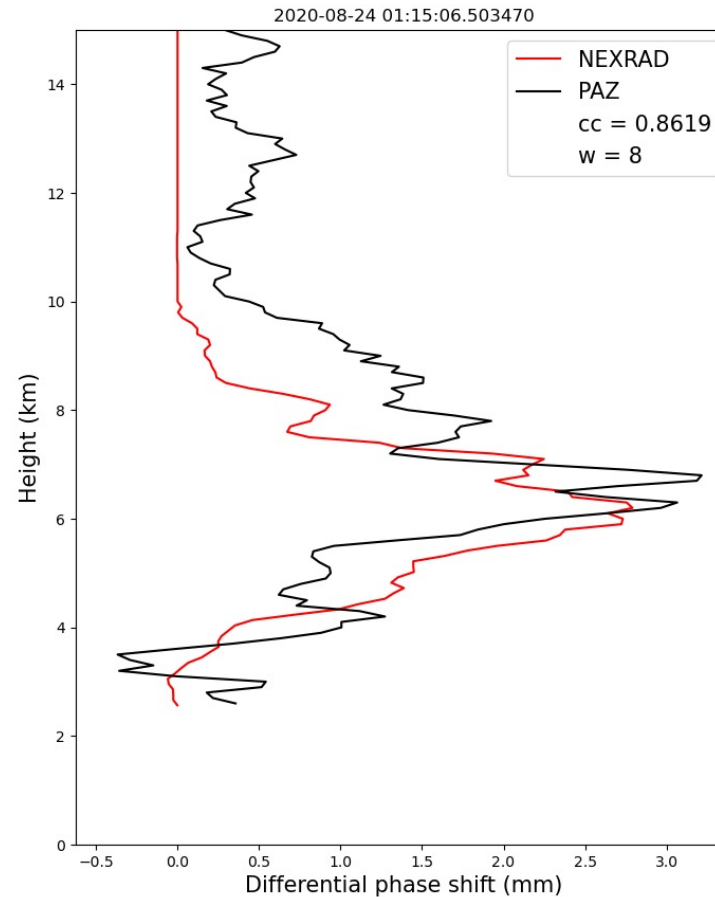
Observations considered as precipitation cases:

- >60% of PRO's area covered by radars
- Mean $\Delta\Phi$ between 0-10km: $Dphi010 > 1.5$ mm

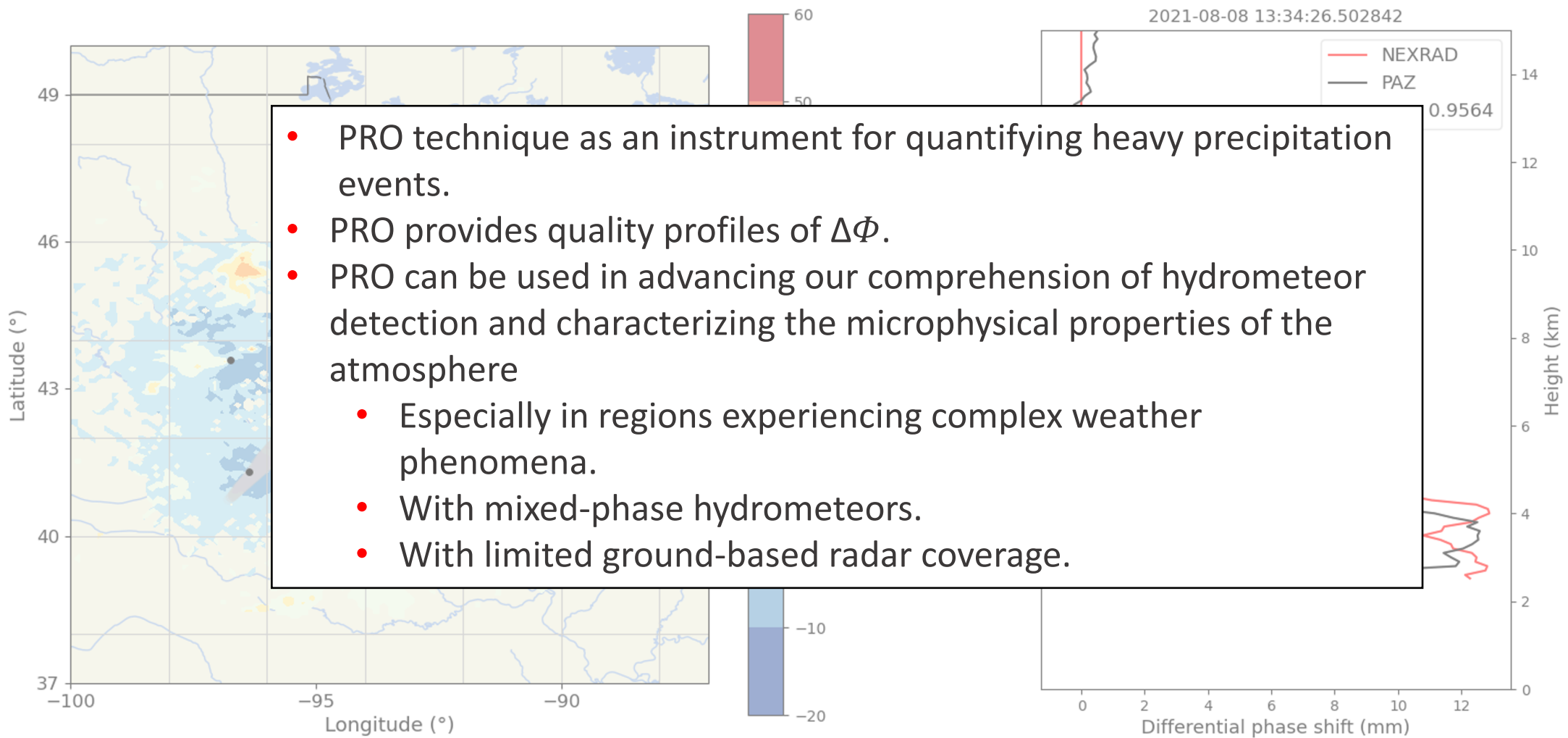


Vertical profiles $\Delta\Phi$

- General good agreement between profiles
- NEXRAD and PAZ have similar comprehension of the observable $\Delta\Phi$
- The peaks of maximum $\Delta\Phi$ exhibit remarkably close values and occur at nearly identical heights
- Better agreement for those observation with peaks at lower altitudes
- For larger $\Delta\Phi$ best fit with smaller window sizes and vice-versa.



Conclusions



References

- Cardellach, E., Oliveras, S., Rius, A., Tomás, S., Ao, C. O., Franklin, G. W., ... & Cerezo, F. (2019). Sensing heavy precipitation with GNSS polarimetric radio occultations. *Geophysical research letters*, 46(2), 1024-1031.
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Thank you!

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